Generative Adversarial Networks (GAN) Saliency Detection, Depth Based Saliency Comparison

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What is saliency prediction?



Saliency prediction algorithms identify eyecatching objects in a scene/quantify how salient each pixel of a scene is.

What is a GAN



Figure: GAN System diagram

GANs are a design of neural network based on two networks:

- Generator To create fake images based off some input
- Discriminator To classify real and fake images

Discriminator

A discriminator is based on a convolutional neural network to classify images.



Figure: Convolutional neural network

A convolutional neural network is based on image convolution to downsample an image into a more processable amount of data. with each convolution more feature maps are generated. Once the images are small enough the data is linearised and densely connected.

CNN Example

image = cv2.imread('uniLogo.png')

image=cv2.cvtColor(image, cv2.COLOR_BGR2RGB)

image=image/255

plt.inshow(image)
plt.axis('off')
plt.show()
print("Shape: ",image.shape)
print("Size: ",image.size,image.size/image.size*100, "%")



Shape: (225, 225, 3) Size: 151875 100.0 %

Figure: Load image code

#Define model

```
model = Sequential()
model.add(Conv2D(25,5,5,input_shape=image.shape))
```

#Print model

```
out-model.predict(image.reshape([1,225, 225, 3]))
out- out[6;; ;, ;]
for in range(0, len(out[0][0]));
    plt.subplot(5,len(out[0][0])/5,i+1)
    plt.inshow(out[;, ;],cmap-plt.cm.binary)
    plt.axis('off')
    plt.show()
    print("Stape: ",out.shape)
    print("Stape: ",out.size,out.size/image.size*100, "%")
```



Figure: Tensorflow single Convolution code

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Generator

A generator is based on a convolutional neural network followed by a de-convolutional neural network.



Figure: Convolutional to de-convolutional neural network

There are two main aims for this project:

- Create a novel saliency prediction algorithm using a GAN.
- Compare saliency prediction with RGB and RGB-D

Methodology

- Choose GAN generator and discriminator design
- **②** Train 3 GANs to each accept: RGB, Depth and RGB-D separately
- Use other combination methods on RGB and depth data to compare ours to.
- Quantify model efficiency

Results

Two different methods were used to quantify model accuracy:

- F-measure
- Receiver operating characteristic curve (ROC)

Both of these are based on True positive rate, false positive rate, true negative rate and false negative rate.

F-Measure

F-Measure is a numeric value calculated as the harmonic mean of precision and recall:

$$F = 2 \cdot \frac{\frac{TP}{TP+FP} \cdot \frac{TP}{TP+FN}}{\frac{TP}{TP+FP} + \frac{TP}{TP+FN}}$$
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- IP True positive rate
- P False positive rate
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F-Measure ranges from 1-0 with 1 meaning 100% true positive rate and 0% false positives/negatives.

Receiver operating characteristic

ROC is a line generated by varying a threshold on an image and comparing that to ground truth.



Figure: Varying threshold on saliency map



Figure: Single ROC



Figure: All ROC in dataset

Results

Model	E Moasuro		Model	F-Measure	AUC
		AUC	GP	0.5607	0.8668
Ours(RGB)	0.7248	0.9227	GBVS (RGB)	0.5113	0.8927
GBVS(RGB)	0.3163	0.7052	Itti (RGB)	0.4221	0.8597
Itti(RGB)	0.3097	0.7380	Ours $(*)$	0 3950	0 7731
LMH	0.1878	0.7646	I MH	0.3208	0 7921
LMH ´	0.1878	0.7646	LMH	0.3930	0.7921



Figure: Olesova results



Figure: NLPR results

Results - Depth



Figure: Our combination methods compared

Image: A math a math

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Future Work

A few ideas:

- Design neural network to take multiple inputs (3/4 channel)
- Run network on a larger epoch system
- Train/Test on similar saliency datasets
- Implement the network in a system such as compression

Conclusion

We set out with the following aims:

- Create a novel saliency prediction algorithm using a GAN.
- Compare saliency prediction with RGB and RGB-D

Any Questions?

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